

**Amendments to the Specification:**

Please replace the paragraph, beginning at page 9, line 21, with the following rewritten paragraph:

The ~~resulting sum~~ steering angle  $\delta_L$  21 is furnished to the steering controller 10 as an input quantity at 22, just as the additional steering angle  $\delta_M$  23. The ~~resulting sum~~ steering angle  $\delta_L$  21 is also sent 26 as an input quantity to the driving dynamics controller 6. Signals or measured quantities of the actuator means, the electric motor 14, are also sent to the steering controller 10 at 24.